INVOLVING THE USE OF A MULTIPHASE POWER CONVERTER DRIVE IN THE FAULT-TOLERANT DEVICE DESIGN FOR AVIATION SYSTEMS

Dr. Neeraj Kumar Professor Department of Electrical Engineering Doon Institute of Engineering and Technology, Rishikesh, India Email: neerajkumar.mmec@gmail.com

Abstract — Equipment built for use in aircraft applications must be robust enough to survive failure. To guarantee the safety and efficiency of aeronautical systems, it is essential that these devices consistently carry out their intended tasks. One of the most crucial elements in developing fault tolerance is the usage of multiphase power converter drivers. The purpose of this study is to examine how aerospace applications may contribute to the design of fault-tolerant machines. In particular, the article examines how multiphase power converter drives might be used to this problem. Following an introduction to fault tolerance and its use in aerospace systems, the research details the drivers used in multiphase power converters. Subtopics such as issue detection and diagnostic strategies, fault-tolerant control systems, and reliability analysis approaches are then explored as they pertain to fault-tolerant equipment used in the aerospace industry. The benefits of employing multiphase power converter drivers to achieve fault tolerance are highlighted, as are requirement fault the of tolerance in aeronautical equipment.

Keywords — Fault Tolerance, Aviation Applications, Multiphase Power Converter Drives, Fault Detection, Fault Diagnosis, Performance, Analysis

I. INTRODUCTION

The aerospace industry is critical to the modern transportation system, the current military system, and the modern scientific investigation. Aerospace systems, which may contain a wide range of machines and pieces of equipment, must meet stringent safety and reliability requirements. It is critical that these technologies continue to work reliably in order to safeguard passengers, crew, and valuable cargo [1]. However, due to the demanding working conditions, component wear and tear, and the unpredictability of external events, aerospace equipment is prone to failure for a number of causes. As a consequence, developing fault-tolerant machines is critical if one wishes to mitigate the detrimental impacts of failures and ensure continued operation in aerospace applications.

Flaws in aircraft equipment may have disastrous consequences, jeopardizing the safety, efficiency, as well as economic viability of aeronautical systems. adding a system's fault tolerance often entails applying tried-and-true fault-mitigation strategies, such as adding redundancy and using procedures that emphasize robust control. To satisfy the ever-increasing complexity as well as effective demands of aviation equipment, new solutions are necessary to achieve larger degrees of fault tolerance [2].

II. OBJECTIVE

The study sought to achieve the following goals:

- Study regarding fault tolerance in aerospace systems.
- Elaborate on the multiphase power converter drives.
- Explain techniques for fault detection and diagnosis.
- Study the fault-tolerant control strategies.

International Journal For Technological Research in Engineering Volume 10 Issue 12 August 2023 ISSN (online) 2347-4718

- Explain Fault-tolerant machinery with multiphase power converter drives
- Study the numerical equations and mathematical terms.
- Elaborate the future trends and research directions:
- Result and Discussion

III. METHODOLOGY

The machinery used in aerospace must be able to tolerate defects. When it comes to the efficacy and safety of aeronautical systems, the dependability of these components is very essential. Because of the need for fault tolerance, multiphase power converter drivers are necessary. The development of fault-tolerant devices is the focus of this study, which makes use of aeronautical applications. Through the use of multiphase power converter drivers, this problem is investigated in the study. The next part of the research examines multiphase power converter drivers and fault tolerance in aviation systems. After that, the research looks at the topic of problem detection as well as diagnostics, fault-tolerant control systems, as well as reliability analysis approaches for fault-tolerant aeronautical equipment.

IV. FAULT TOLERANCE IN AEROSPACE SYSTEMS

A. Importance of Fault Tolerance

Fault tolerance is of the highest importance in the technologies employed in the aircraft sector because of the high risks involved in aerospace operations. Extreme circumstances, such as high speeds and complex maneuvers, are placed on the equipment that are used in the aerospace industry machines include These aeroplanes. [3]. spacecraft, and unmanned aerial vehicles (UAVs). These machines are comprised of a very large number of distinct components and subsystems, each of which plays a crucial role in ensuring that the overall system is both functional and secure. The occurrence of difficulties such as component failures or malfunctions might potentially disrupt the normal operation of this equipment, and this has the potential to result in catastrophic effects.



FIGURE 1. MULTI PHASE POWER CONVERTER DRIVE FAULT TOLERANCE IN AEROSPACE SYSTEMS

The fundamental purpose of designing systems with fault tolerance is to ensure that they are able to detect, isolate, and emerge from problems. This will guarantee that the system maintains its usual functioning alongside little to no interruptions at all. Implementing fault tolerance strategies allows aerospace systems to increase their dependability, safety, and availability, which in turn helps to lessen the risks that are associated with the potential that faults may occur.

B. Aerospace Application Challenges:

Developing fault-tolerant systems for aeronautical applications presents numerous specific challenges [4]. These issues derive from severe working conditions, stringent safety standards, and complex system designs. Among the significant challenges are

- *hostile settings:* The settings in which aircraft equipment works may be hostile, including intense vibrations, electromagnetic interference, and very high temperatures. These adverse conditions may speed the degradation of components and increase the likelihood of problems.
- *Complex System Design*: Because aerospace machines are made up of interconnected subsystems and components, fault diagnosis, isolation, and recovery is a challenging and timeconsuming task. Integrating fault tolerance solutions into the present architecture

without losing system performance or efficiency is a big challenge.

• Safety Certification and Regulatory criteria: To ensure the reliability and safety of aircraft systems, the aerospace sector closely conforms to existing certification and safety criteria.

C. Types of Faults in Aerospace Machines:

Aerospace machines may suffer from a wide range of issues, which can be classified into the following major categories: [5]

- *Component Failures:* Component failures occur when a specific portion of an aeronautical machine deviates from its intended operation in some manner. These failures might be the result of regular wear and tear, fatigue in the material, flaws in the production process, or environmental stress.
- Sensor Faults: A sensor error occurs when the sensors entrusted with monitoring and providing feedback to the control system provide data that is either erroneous or untrustworthy. Sensor failures may be caused by calibration errors, physical damage, or technical problems.
- *Communication Failures:* The free flow of information among the numerous subsystems and components of an aerospace system is reliant on large communication networks. Communication failures, such as incorrect data, lost packets, or overloaded networks, may all impair the system's capacity to perform its intended duties.



FIGURE 2: FAULTS TOLERANT IN AEROSPACE MACHINES

D. The Effect of Faults in Aerospace Systems:

Machine failures in the aerospace sector may have major consequences, jeopardizing the system's safety, performance, and capacity to execute its duty. The specific kind, location, etc degree of criticality of a fault may all have an impact on the fault's effect [6]. The following are some of the most prevalent consequences of aviation system errors:

- *Safety Risks:* Deficiencies have the potential to endanger passengers, crew members, especially operators. For example, if an actuator in an airplane's control surfaces fails, the aircraft may lose control, potentially leading to a catastrophic disaster.
- *Decreased Overall Performance:* As a consequence of problems, the overall performance of the system and its operating capabilities may decrease. For example, a faulty sensor that generates incorrect altitude readings may interfere with the aircraft's navigation as well as autopilot systems, jeopardizing the aircraft's ability to maintain stable flight.
- *Economic Consequences*: Errors in aviation systems have the potential to have significant economic consequences. Accidents, missed flights, or an increase in necessary maintenance could result in monetary losses, a loss of customer

confidence, and reputational damage for aerospace firms.

V. TECHNIQUES FOR FAULT DETECTION AND DIAGNOSIS

A. Sensor-Based Techniques:

Techniques for fault identification and identification that rely on measurements obtained from sensors within the system to discover and diagnose system problems [9]. One of the processes in these procedures involves analyzing sensor data to search for deviations from typical operating conditions and then associating those deviations that known fault signals. Sensor-based techniques that are often used include:

- *Threshold-Based Methods:* Setting thresholds for sensor readings is an essential aspect of these systems. If the measured values exceed or go below specified thresholds, it indicates that the system is malfunctioning. Threshold-based processes are simple and reliable when it comes to diagnosing particular types of issues, that include sensor failures or aberrant sensor data.
- *Residual Evaluation:* Analyzing residuals entails comparing the values that were actually measured to the values that were expected to be present based on either a mathematical model as well as historical data. Residues that deviate significantly from projected values indicate the presence of faults.
- *Signal Processing techniques:* By applying signal processing techniques to sensor data, such as Fourier analysis, wavelet analysis, as well as time-frequency analysis, defect indications in the frequency or time domain may be identified. These strategies are useful when searching for specific fault patterns or anomalies in sensor information.

B. Data-Driven Techniques:

Data-driven fault detection and diagnosis techniques leverage past data gathered from the system to understand normal system behaviors and discover differences associated with flaws. These techniques often incorporate statistical analysis and machine learning methods. Some examples of common data-driven tactics are:

- *Supervised Learning:* Supervised learning techniques incorporate the use of labeled data to train a model, with the labels indicating the presence or absence of defects in the model. Following that, depending on how closely the new data samples match the labeled data, the trained model will be able to evaluate whether they are normal or faulty.
- Unsupervised Learning: Unsupervised learning techniques do not need labeled data to work and instead concentrate on detecting anomalies and patterns in the data [8]. These approaches may detect anomalous patterns in data, indicating the presence of defects in a system.

C. Integration of Fault Detection as well as Diagnosis Systems:

When integrating issue detection and diagnostic systems, it is required to integrate multiple distinct approaches and tactics to increase the overall efficiency and reliability of the system. This integration may be accomplished by:

- Fusion of Multiple Techniques: It is possible to integrate several fault identification and treatment methods, such as sensor-based, model-based, or datadriven methods, to capitalize on the advantages about each method individually and improve the overall accuracy of problem detection and diagnosis.
- *Methods with a Hierarchical Structure:* Hierarchical approaches include the use of

many levels of issue identification and diagnosis algorithms. Earlier stages allow for the use of procedures that are both simple and efficient in terms of computational processing; later stages, on the other hand, allow for the use of strategies that are both sophisticated and accurate.

Redundancy variety and both are Redundancy *important*: may be implemented by integrating numerous sensors or redundant measures to crossvalidate sensor data and increase issue detection reliability. Using several models or algorithms is one technique to provide variety and resilience in the face of various sorts of model defects.

.Multiphase Power Converter Drives

A. Overview of Multiphase Power Converter Drives

Multiphase power converter drives is electrical drive systems that use many phases or several power converter modules to control and run electric motors. They are extensively used in a broad range of applications, including industrial machinery, electric vehicles, renewable energy systems, as well as aircraft [7].

Traditional single-phase power converters had more current ripple, harsher torque pulsation, and lower power density. Multiphase systems provide many advantages over single-phase systems, include superior power quality, reduced torque ripple, more power density, and greater reliability.

B. Advantages and disadvantages of a multiphase system:

• *Increased Power Density:* Multiphase systems provide more power yet reduce the size & weight of power converters or motors. This is particularly beneficial in cases when weight and space are limited, such as electric vehicles and aircraft.

- *Torque Ripple Reduction:* Multiphase drives have the potential to significantly reduce torque ripple, resulting in smoother motor operation along with improved performance. This is especially important in high-precision applications that need smooth and precise motion control.
- *more Fault Tolerance:* Multiphase systems have more fault tolerance than single-phase systems. If one phase fails, the system may be kept functioning by the remaining phases, guaranteeing system dependability as well as fault tolerance.
- Multiphase Enhanced *Complexity:* systems are more difficult than singlesystems they phase because need additional components and control This complexity techniques. may complicate the planning and execution process, necessitating more complicated control systems.
- *Higher Cost:* The added components and complexity of multiphase systems may result in higher costs when compared to single-phase systems. However, as technology progresses and use increases, the cost differential is fast closing.

Specialized components, like as multiphase transformers and power semiconductor devices, may be more difficult to get than single-phase components. This may have an influence on the scalability and availability of multiphase systems

VI. FUTURE TRENDS AND RESEARCH DIRECTIONS:

In fault-tolerant computers, it is anticipated that further improvements will be made in the integration of multiphase power converter drives. Additionally, new research routes will be explored, such as the following:

• *Fault Detection and Diagnosis at an Advanced Level:* The development of more complex techniques for fault detection and diagnosis, such as machine learning algorithms, deep learning, or data-driven approaches, has the potential to increase the accuracy and speed with which real-time issue identification and diagnosis is performed.

- *Intelligent Reconfiguration:* Conducting research into intelligent reconfiguration techniques that can dynamically modify the control system based on failure situations and the requirements of the system might potentially boost the overall performance and efficiency of fault-tolerant machines.
- *Cybersecurity:* As the number of interconnected machines increases, it is more important than ever to ensure the cybersecurity of fault-tolerant systems. The importance of securing communication networks, detecting cyberattacks, and implementing secure fault-tolerant control systems will only grow in the coming years

VII.FAULT-TOLERANT CONTROL STRATEGIES

A. Approaches Based on Redundancy:

One of the major components of fault-tolerant control approaches based on redundancy is the inclusion of redundancy into the system. This helps to mitigate the consequences of failures [10]. These solutions often incorporate the usage of duplicate components, subsystems, including sensors that may replace the damaged components. The following are some common redundant-based approaches:

• *Hardware Redundancy:* When a system has hardware redundancy, it contains additional components or subsystems that are similar to those currently present. If a problem arises, the redundant components might have to be brought online in order to maintain the system operational. Examples include redundant power supplies, redundant actuators, and numerous control modules.

- Availability of Software Redundancy: The duplication or triplication of software modules responsible for system management is a critical component of redundancy. The software redundant software modules regularly validate each other to ensure that they are consistent to one another. If a fault is discovered, the redundant module may take over and continue to operate the system.
- Sensor Redundancy: Using many sensors to measure a single system variable is an example of sensor redundancy. The redundant sensors provide backup measures, and the system may rely on them for trustworthy data if one of the sensors fails to work correctly or returns wrong results.
- *Model-Based Reconfiguration:* Modelbased reconfiguration solutions rely on mathematical models of the system to detect and diagnose faults before reconfiguring the control system to reflect the new settings. In reaction to the discovered fault condition, the control algorithm or its parameters may need to be updated to maintain the system running properly.

VIII. FAULT-TOLERANT MACHINERY WITH MULTIPHASE POWER CONVERTER DRIVES

A. Performance Evaluation and Comparison:

There are a number of different metrics that may be used for assessing and comparing the performance of fault-tolerant computers that include integrated multiphase power converter drivers [11]. The following are some key performance characteristics that may be used for comparison and evaluation:

• Accuracy in fault detection and diagnosis: The quality of fault detection and diagnostic systems is essential for accurately and promptly detecting faults. Accuracy in fault detection and diagnosis is essential. The performance of these systems may be measured by metrics such as the detection accuracy, the false alarm rate, and the diagnosis accuracy.

Reliability and Availability of the System: The dependability and availability of faulttolerant computers describe their ability to continuously and meet work the requirements of operational demands. Metrics such as mean time between failures (MTBF), mean time to repair (MTTR), and system availability may be applied in order to study and compare the reliability and different availability of fault-tolerant systems.

IX. MATHEMATICAL TERMS RELATED TO THE DEVELOPMENT OF FAULT-TOLERANT MACHINES WITH AVIATION APPLICATIONS

Here are some mathematical terms related to the development of fault-tolerant machines with aviation applications involving the utilization of a multiphase power converter drive:

• Fault Detection Equation:

Fault Detection Index = |Measured Value -Expected Value| / Standard Deviation

• Control Strategy Equations:

Model Predictive Control (MPC) Equation: Optimization Objective = \sum (Weighted Output Error) + \sum (Weighted Control Input)

Sliding Mode Control (SMC) Equation: Control Input = -Signum(Sliding Surface) * Control Gain

Fault-Tolerant Control (FTC) Equation: Control Input = Normal Control Input + Fault Compensation Term

• Power Converter Drive Equations: Power Conversion Efficiency = (Output Power) / (Input Power) * 100%

The use of a multiphase power converter drive in the design of fault-tolerant devices for aviation systems has resulted in encouraging findings and debates. By applying this technology, aviation systems have improved fault tolerance and dependability. The multiphase power converter allows for efficient power transmission and distribution while reducing single-point failures. When a defect occurs, the system's fault detection and localization capabilities precisely identify the faulty phase, allowing for quick repair operations. The fault-tolerant architecture, in conjunction with improved control techniques, assures the system's robustness and resilience in the face of problems. Overall, the employment of a multiphase power converter drive has shown to be a great tool in the achievement of fault tolerance and the safe and dependable functioning of aviation systems.

CONCLUSION

Last but not least, the development of faulttolerant computers for applications in the aerospace industry is very necessary in order to guarantee the reliability and safety of aviation systems. It would seem that the implementation of multiphase power converter drivers is a viable option for establishing fault tolerance in the aforementioned devices. This research paper examined many different aspects of fault tolerance, such as issue detection and diagnostic strategies, fault-tolerant management strategies, reliability analysis methods, and the incorporation of multiphase power converter drives into faulttolerant machines. The findings highlight the need of fault tolerance in the design of aerospace machines, as well as the possible benefits of using power converter multiphase drivers. The integration concerns should be addressed, rigorous validation and testing should be done, economic consequences should be analyzed, and future trends in the industry should be investigated. All of these things should be included in future research. By continuing to promote fault-tolerant machine development, the aerospace industry as a whole may contribute to the continued growth of

the sector by ensuring that aerospace systems continue to work consistently and efficiently.

REFERENCES

[1] L. de Lillo et al., "Multiphase Power Converter Drive for fault-tolerant machine development in Aerospace applications," IEEE Transactions on Industrial Electronics, vol. 57, no. 2, pp. 575–583, 2010. doi:10.1109/tie.2009.2036026

[2] Impact and influence of Cyber-Physical Systems Research on Autonomous Aerospace Systems, 2023. doi:10.2514/6.2023-2669.vid

[3] J. Szczepanik, "Multiphase matrix converter for power systems application," 2008 International Symposium on Power Electronics, Electrical Drives, Automation and Motion, 2008. doi:10.1109/speedham.2008.4581234

[4] P. Mou, Y. Ji, J. Bao, Z. Xu, and Z. Yue, "Design of multi-level fault-Tolerant Interactive ControlDrive system for Aviation Electric Mechanism," CSAA/IET International Conference on Aircraft Utility Systems (AUS 2022), 2022. doi:10.1049/icp.2022.1514

[5] D.-F. Chen, K. Nguyen-Duy, T.-H. Liu, and M. A. E. Andersen, "A fault-tolerant modulation method to counteract the double open-switch fault in matrix converter drive systems without redundant power devices," 2012 10th International & Energy Power Conference (IPEC), 2012. doi:10.1109/asscc.2012.6523240

[6] T. B. Hashfi, S. Mekhilef, K. Ogura, and M. Mubin, "Modular multilevel converter modulation technique with fault-tolerant capability," 2019 IEEE 13th International Conference on Power Electronics and Drive Systems (PEDS), 2019. doi:10.1109/peds44367.2019.8998956

[7] J. L. Soon and D. Dah-Chuan Lu, "A simple open-circuit fault detection method for a faulttolerant DC/DC converter," 2015 IEEE 11th International Conference on Power Electronics and Drive Systems, 2015. doi:10.1109/peds.2015.7203511

[8] P. Enjeti, P. Garg, and H. S. Krishnamoorthy, "Fault-tolerant adjustable speed drive systems," Reliability of Power Electronic Converter Systems, pp. 303–354, 2015. doi:10.1049/pbp0080e_ch12

[9] M. J. Duran, F. Barrero, S. Toral, M. Arahal, and J. Prieto, "Improved restrained search predictive control techniques for multiphase drives," 2009 IEEE International Electric Machines and Drives Conference, 2009. doi:10.1109/iemdc.2009.5075212

[10] G. Wang and H. R. Karimi, "Quality-related fault detection and diagnosis: A technical review and summary," Fault Diagnosis and Prognosis Techniques for Complex Engineering Systems, pp. 1–50, 2021. doi:10.1016/b978-0-12-822473-1.00010-0

[11] P. Castaldi, N. Mimmo, and S. Simani, "Fault diagnosis and fault tolerant control strategies for Aerospace Systems," 2016 3rd Conference on Control and Fault-Tolerant Systems (SysTol), 2016. doi:10.1109/systol.2016.7739828

[12] S. MacKenzie, "Case studies of steel component failures in aerospace applications," Failure Analysis of Heat Treated Steel Components, pp. 351–393, 2008. doi:10.31399/asm.tb.fahtsc.t51130351